

Technical documentation



Support & training



DRV8300U SLVSGY3A – JULY 2022 – REVISED OCTOBER 2022

## DRV8300U: 100-V Three-Phase BLDC Gate Driver

## 1 Features

- 100-V Three Phase Half-Bridge Gate driver
  - Drives N-Channel MOSFETs (NMOS)
  - Gate Driver Supply (GVDD): 5-20 V
  - MOSFET supply (SHx) support upto 100 V
- Integrated Bootstrap Diodes (DRV8300UD devices)
- Supports Inverting and Non-Inverting INLx inputs
- Bootstrap gate drive architecture
  - 750-mA source current
  - 1.5-A sink current
- Supports up to 15S battery powered applications
- Higher BSTUV (8V typ) and GVDDUV (7.6V typ) threshold to support standard MOSFETs
- Low leakage current on SHx pins (<55 μA)</li>
- Absolute maximum BSTx voltage upto 125-V
- Supports negative transients upto -22-V on SHx
- Built-in cross conduction prevention
- Adjustable deadtime through DT pin for QFN package variants
- Fixed deadtime insertion of 200 nS for TSSOP package variants
- Supports 3.3-V and 5-V logic inputs with 20 V Abs max
- 4 nS typical propogation delay matching
- Compact QFN and TSSOP packages
- Efficient system design with Power Blocks
- Integrated protection features
  - BST undervoltage lockout (BSTUV)
  - GVDD undervoltage (GVDDUV)

## 2 Applications

- E-Bikes, E-Scooters, and E-Mobility
- Fans, Pumps, and Servo Drives
- Brushless-DC (BLDC) Motor Modules and PMSM
- Cordless Garden and Power Tools, Lawnmowers
- Cordless Vacuum Cleaners
- Drones, Robotics, and RC Toys
- Industrial and Logistics Robots

## **3 Description**

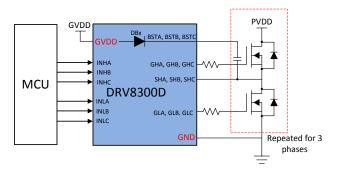
DRV8300U is 100-V three half-bridge gate drivers, capable of driving high-side and low-side N-channel power MOSFETs. The DRV8300UD generates the correct gate drive voltages using an integrated bootstrap diode and external capacitor for the high-side MOSFETs. GVDD is used to generate gate drive voltage for the low-side MOSFETs. The Gate Drive architecture supports peak up to 750-mA source and 1.5-A sink currents.

The phase pins SHx is able to tolerate the significant negative voltage transients; while high side gate driver supply BSTx and GHx is able to support to higher positive voltage transients (125-V) abs max voltage which improves robustness of the system. Small propagation delay and delay matching specifications minimize the dead-time requirement which further improves efficiency. Undervoltage protection is provided for both low and high side through GVDD and BST undervoltage lockout.

#### Device Information<sup>(1)</sup>

PART NUMBER	IBER PACKAGE BODY SIZ		
DRV8300UDPW	TSSOP (20)	6.40 mm × 4.40 mm	
DRV8300UDIPW	TSSOP (20)	6.40 mm × 4.40 mm	
DRV8300UDRGE	VQFN (24)	4.00 mm × 4.00 mm	

(1) For all available packages, see the orderable addendum at the end of the data sheet.



#### Simplified Schematic for DRV8300UD



## **Table of Contents**

1 F	eatures1
2 A	pplications1
	escription1
4 R	evision History2
	evice Comparison Table
6 P	n Configuration and Functions4
	pecifications
7	1 Absolute Maximum Ratings6
	2 ESD Ratings Comm6
	3 Recommended Operating Conditions
7	4 Thermal Information7
7	5 Electrical Characteristics7
7	.6 Timing Diagrams9
7	7 Typical Characteristics9
	etailed Description11
8	1 Overview
	2 Functional Block Diagram12

8.3 Feature Description	.13
8.4 Device Functional Modes	
9 Application and Implementation	. 16
9.1 Application Information	. 16
9.2 Typical Application	. 17
10 Power Supply Recommendations	.20
11 Layout	.21
11.1 Layout Guidelines	21
11.2 Layout Example	. 21
12 Device and Documentation Support	.22
12.1 Receiving Notification of Documentation Updates.	.22
12.2 Support Resources	. 22
12.3 Trademarks	.22
12.4 Electrostatic Discharge Caution	.22
12.5 Glossary	.22
13 Mechanical, Packaging, and Orderable	
Information	. 22

## **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Cł	nanges from Revision * (July 2022) to Revision A (October 2022)	Page
•	Updated device status to Production Data	1



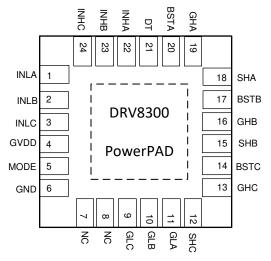
## **5** Device Comparison Table

Device Variants	Package	Integrated Bootstrap Diode	GLx polarity with respect to INLx Input	Deadtime
DRV8300UD	20-Pin TSSOP	Yes	Inverted	Fixed
DRV8300UDI		Yes	Non-Inverted	Fixed
DRV8300UD	24-Pin VQFN	Yes	Non-Inverted or Inverted	Variable

#### Table 5-1. DRV8300 vs DRV8300U comparison

Parameters	DRV8300	DRV8300U
GVDDUV rising	4.6-V (typ)	8.3-V (typ)
GVDDUV falling	4.35-V (typ)	8-V (typ)
BSTUV rising	4.2-V (typ)	8-V (typ)
BSTUV falling	4-V (typ)	7.6-V(typ)

## **6** Pin Configuration and Functions



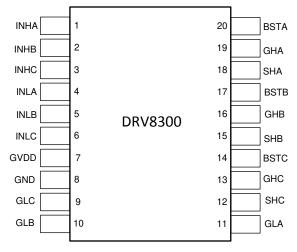
## Figure 6-1. DRV8300UD RGE Package 24-Pin VQFN With Exposed Thermal Pad Top View

PIN TYPE <sup>(1)</sup>			DECODIDION		
NAME	NO.		DESCRIPTION		
BSTA	20	0	Bootstrap output pin. Connect capacitor between BSTA and SHA		
BSTB	17	0	Bootstrap output pin. Connect capacitor between BSTB and SHB		
BSTC	14	0	Bootstrap output pin. Connect capacitor between BSTC and SHC		
DT	21	I	Deadtime input pin. Connect resistor to ground for variable deadtime, fixed deadtime when left it floating		
GHA	19	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.		
GHB	16	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.		
GHC	13	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.		
GLA	11	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.		
GLB	10	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.		
GLC	9	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.		
INHA	22	I	High-side gate driver control input. This pin controls the output of the high-side gate driver.		
INHB	23	I	High-side gate driver control input. This pin controls the output of the high-side gate driver.		
INHC	24	I	High-side gate driver control input. This pin controls the output of the high-side gate driver.		
INLA	1	I	Low-side gate driver control input. This pin controls the output of the low-side gate driver.		
INLB	2	I	Low-side gate driver control input. This pin controls the output of the low-side gate driver.		
INLC	3	I	Low-side gate driver control input. This pin controls the output of the low-side gate driver.		
MODE	5	I	Mode Input controls polarity of GLx compared to INLx inputs. Mode pin floating: GLx output polarity same(Non-Inverted) as INLx input Mode pin to GVDD: GLx output polarity inverted compared to INLx input		
NC	7, 8	NC	No internal connection. This pin can be left floating or connected to system ground.		
GND	6	PWR	Device ground.		
SHA	18	I	High-side source sense input. Connect to the high-side power MOSFET source.		
SHB	15	I	High-side source sense input. Connect to the high-side power MOSFET source.		
SHC	12	I	High-side source sense input. Connect to the high-side power MOSFET source.		
GVDD	4	PWR	Gate driver power supply input. Connect a X5R or X7R, GVDD-rated ceramic and greater then or equal to 10-uF local capacitance between the GVDD and GND pins.		

## Table 6-1. Pin Functions—24-Pin DRV8300U Devices

(1) PWR = power, I = input, O = output, NC = no connection





## Figure 6-2. DRV8300UD, DRV8300UDI PW Package 20-Pin TSSOP Top View

PIN TYPE1			DESCRIPTION	
NAME	NO.		DESCRIPTION	
BSTA	20	0	Bootstrap output pin. Connect capacitor between BSTA and SHA	
BSTB	17	0	Bootstrap output pin. Connect capacitor between BSTB and SHB	
BSTC	14	0	Bootstrap output pin. Connect capacitor between BSTC and SHC	
GHA	19	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.	
GHB	16	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.	
GHC	13	0	High-side gate driver output. Connect to the gate of the high-side power MOSFET.	
GLA	11	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.	
GLB	10	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.	
GLC	9	0	Low-side gate driver output. Connect to the gate of the low-side power MOSFET.	
INHA	1	I	High-side gate driver control input. This pin controls the output of the high-side gate driver.	
INHB	2	I	gh-side gate driver control input. This pin controls the output of the high-side gate driver.	
INHC	3	I	gh-side gate driver control input. This pin controls the output of the high-side gate driver.	
INLA	4	I	ow-side gate driver control input. This pin controls the output of the low-side gate driver.	
INLB	5	I	Low-side gate driver control input. This pin controls the output of the low-side gate driver.	
INLC	6	I	Low-side gate driver control input. This pin controls the output of the low-side gate driver.	
GND	8	PWR	Device ground.	
SHA	18	I	High-side source sense input. Connect to the high-side power MOSFET source.	
SHB	15	I	High-side source sense input. Connect to the high-side power MOSFET source.	
SHC	12	I	High-side source sense input. Connect to the high-side power MOSFET source.	
GVDD	7	PWR	Gate driver power supply input. Connect a X5R or X7R, GVDD-rated ceramic and greater then or equal to 10-uF local capacitance between the GVDD and GND pins.	

#### Table 6-2. Pin Functions—20-Pin DRV8300U Devices

1. PWR = power, I = input, O = output, NC = no connection



## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Gate driver regulator pin voltage	GVDD	-0.3	21.5	V
Bootstrap pin voltage	BSTx	-0.3	125	V
Bootstrap pin voltage	BSTx with respect to SHx	-0.3	21.5	V
Logic pin voltage	INHx, INLx, MODE, DT	-0.3	V <sub>GVDD</sub> +0.3	V
High-side gate drive pin voltage	GHx	-22	125	V
High-side gate drive pin voltage	GHx with respect to SHx	-0.3	22	V
Transient 500-ns high-side gate drive pin voltage	GHx with respect to SHx	-5	22	V
Low-side gate drive pin voltage	GLx	-0.3	V <sub>GVDD</sub> +0.3	V
Transient 500-ns low-side gate drive pin voltage	GLx	-5	V <sub>GVDD</sub> +0.3	V
High-side source pin voltage	SHx	-22	110	V
Ambient temperature, T <sub>A</sub>		-40	125	°C
Junction temperature, T <sub>J</sub>		-40	150	°C
Storage temperature, T <sub>stg</sub>		-65	150	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime

## 7.2 ESD Ratings Comm

			VALUE	UNIT	
	Electrostatic	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	V	
V <sub>(ESD)</sub>	discharge	Charged device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±250	v	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating temperature range (unless otherwise noted)

			MIN	NOM MAX	UNIT
V <sub>GVDD</sub>	Power supply voltage	GVDD	8.7	20	V
V <sub>SHx</sub>	High-side source pin voltage	SHx	-2	85	V
V <sub>SHx</sub>	Transient 2µs high-side source pin voltage	SHx	-22	85	V
V <sub>BST</sub>	Bootstrap pin voltage	BSTx	5	105	V
V <sub>BST</sub>	Bootstrap pin voltage	BSTx with respect to SHx	5	20	V
V <sub>IN</sub>	Logic input voltage	INHx, INLx, MODE, DT	0	GVDD	V
f <sub>PWM</sub>	PWM frequency	INHx, INLx	0	200	kHz
V <sub>SHSL</sub>	Slew rate on SHx pin (DRV8300UD and DRV8300UDI)			2	V/ns
C <sub>BOOT</sub> <sup>(1)</sup>	Capacitor between BSTx and SHx (DRV8300UD and DRV8300UDI)			1	μF
T <sub>A</sub>	Operating ambient temperature	•	-40	125	°C
TJ	Operating junction temperature		-40	150	°C

(1) Current flowing through boot diode ( $D_{BOOT}$ ) needs to be limited for  $C_{BOOT} > 1\mu F$ 



#### 7.4 Thermal Information

		DRV8		
	THERMAL METRIC <sup>(1)</sup>	PW (TSSOP)	RGE (VQFN)	UNIT
		20 PINS	24 PINS	
R <sub>0JA</sub>	Junction-to-ambient thermal resistance	97.4	49.3	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	38.3	42.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	48.8	26.5	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	4.3	2.2	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	48.4	26.4	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	11.5	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

#### 7.5 Electrical Characteristics

8.7 V  $\leq$  V<sub>GVDD</sub>  $\leq$  20 V, -40°C  $\leq$  T<sub>J</sub>  $\leq$  150°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
POWER SUF	PLIES (GVDD, BSTx)				L	
	GVDD standby mode current	INHx = INLX = 0; V <sub>BSTx</sub> = V <sub>GVDD</sub>	400	800	1400	μA
I <sub>GVDD</sub>	GVDD active mode current	INHx = INLX = Switching @20kHz; V <sub>BSTx</sub> = V <sub>GVDD</sub> ; NO FETs connected	400	825	1400	μA
IL <sub>BSx</sub>	Bootstrap pin leakage current	$V_{BSTx} = V_{SHx} = 85V; V_{GVDD} = 0V$	2	4	7	μA
IL <sub>BS_TRAN</sub>	Bootstrap pin active mode transient leakage current	INHx = Switching@20kHz	30	105	220	μA
IL <sub>BS_DC</sub>	Bootstrap pin active mode leakage static current	INHx = High	30	85	150	μA
IL <sub>SHx</sub>	High-side source pin leakage current	INHx = INLX = 0; V <sub>BSTx</sub> - V <sub>SHx</sub> = 12V; V <sub>SHx</sub> = 0 to 85V	30	55	80	μA
LOGIC-LEVE	L INPUTS (INHx, INLx, MODE)					
V <sub>IL_MODE</sub>	Input logic low voltage	Mode pin			0.6	V
VIL	Input logic low voltage	INLx, INHx pins			0.8	V
V <sub>IH_MODE</sub>	Input logic high voltage	Mode pin	3.7			V
V <sub>IH</sub>	Input logic high voltage	INLx, INHx pins	2.0			V
V <sub>HYS_MODE</sub>	Input hysteresis	Mode pin	1600	2000	2400	mV
V <sub>HYS</sub>	Input hysteresis	INLx, INHx pins	40	100	260	mV
		V <sub>PIN</sub> (Pin Voltage) = 0 V; INLx in non- inverting mode	-1	0	1	μA
I <sub>IL_INLx</sub>	INLx Input logic low current	V <sub>PIN</sub> (Pin Voltage) = 0 V; INLx in inverting mode	5	20	30	μA
		V <sub>PIN</sub> (Pin Voltage) = 5 V; INLx in non- inverting mode	5	20	30	μA
I <sub>IH_INLx</sub>	INLx Input logic high current	V <sub>PIN</sub> (Pin Voltage) = 5 V; INLx in inverting mode	0	0.5	1.5	μA
IIL	INHx, MODE Input logic low current	V <sub>PIN</sub> (Pin Voltage) = 0 V;	-1	0	1	μA
IIH	INHx, MODE Input logic high current	V <sub>PIN</sub> (Pin Voltage) = 5 V;	5	20	30	μA
R <sub>PD_INHx</sub>	INHx Input pulldown resistance	To GND	120	200	280	kΩ
R <sub>PD_INLx</sub>	INLx Input pulldown resistance	To GND, INLx in non-inverting mode	120	200	280	kΩ
R <sub>PU_INLx</sub>	INLx Input pullup resistance	To INT_5V, INLx in inverting mode	120	200	280	kΩ
R <sub>PD_MODE</sub>	MODE Input pulldown resistance	To GND	120	200	280	kΩ
GATE DRIVE	RS (GHx, GLx, SHx, SLx)	· · · · · · · · · · · · · · · · · · ·			I	



#### 8.7 V $\leq$ V<sub>GVDD</sub> $\leq$ 20 V, -40°C $\leq$ T<sub>J</sub> $\leq$ 150°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>GHx_LO</sub>	High-side gate drive low level voltage	ligh-side gate drive low level voltage I <sub>GLx</sub> = -100 mA; V <sub>GVDD</sub> = 12V; No FETs connected				
V <sub>GHx_HI</sub>	High-side gate drive high level voltage (V <sub>BSTx</sub> - V <sub>GHx</sub> )	I <sub>GHx</sub> = 100 mA; V <sub>GVDD</sub> = 12V; No FETs connected	0.3	0.6	1.2	V
V <sub>GLx_LO</sub>	Low-side gate drive low level voltage	I <sub>GLx</sub> = -100 mA; V <sub>GVDD</sub> = 12V; No FETs connected	0	0.15	0.35	V
V <sub>GLx_HI</sub>	Low-side gate drive high level voltage $(V_{GVDD} - V_{GHx})$	I <sub>GHx</sub> = 100 mA; V <sub>GVDD</sub> = 12V; No FETs connected	0.3	0.6	1.2	V
I <sub>DRIVEP_HS</sub>	High-side peak source gate current	GHx-SHx = 12V	400	750	1200	mA
I <sub>DRIVEN_HS</sub>	High-side peak sink gate current	GHx-SHx = 0V	850	1500	2100	mA
IDRIVEP_LS	Low-side peak source gate current	GLx = 12V	400	750	1200	mA
IDRIVEN_LS	Low-side peak sink gate current	GLx = 0V	850	1500	2100	mA
t <sub>PD</sub>	Input to output propagation delay	INHx, INLx to GHx, GLx; $V_{GVDD} = V_{BSTx}$ - $V_{SHx} > 8V$ ; SHx = 0V, No load on GHx and GLx	70	125	180	ns
t <sub>PD_match</sub>	Matching propagation delay per phase	GHx turning OFF to GLx turning ON, GLx turning OFF to GHx turning ON; $V_{GVDD}$ = $V_{BSTx} - V_{SHx} > 8V$ ; SHx = 0V, No load on GHx and GLx	-30	±4	30	ns
tPD_match	Matching propagation delay phase to phase	GHx/GLx turning ON to GHy/GLy turning ON, GHx/GLx turning OFF to GHy/GLy turning OFF; $V_{GVDD} = V_{BSTx} - V_{SHx} > 8V$ ; SHx = 0V, No load on GHx and GLx	-30	±4	30	ns
t <sub>R_GLx</sub>	GLx rise time (10% to 90%)	C <sub>LOAD</sub> = 1000 pF; V <sub>GVDD</sub> = V <sub>BSTx</sub> - V <sub>SHx</sub> > 8V; SHx = 0V	10	24	50	ns
t <sub>R_GHx</sub>	GHx rise time (10% to 90%)	C <sub>LOAD</sub> = 1000 pF; V <sub>GVDD</sub> = V <sub>BSTx</sub> - V <sub>SHx</sub> > 8V; SHx = 0V	10	24	50	ns
t <sub>F_GLx</sub>	GLx fall time (90% to 10%)	C <sub>LOAD</sub> = 1000 pF; V <sub>GVDD</sub> = V <sub>BSTx</sub> - V <sub>SHx</sub> > 8V; SHx = 0V	5	12	30	ns
t <sub>F_GHx</sub>	GHx fall time (90% to 10%)	$C_{LOAD}$ = 1000 pF; $V_{GVDD}$ = $V_{BSTx}$ - $V_{SHx}$ > 8V; SHx = 0V	5	12	30	ns
		DT pin floating	150	215	280	ns
taria	Gate drive dead time	DT pin connected to GND	150	215	280	ns
<sup>I</sup> DEAD		40 k $\Omega$ between DT pin and GND	150	200	260	ns
		400 k $\Omega$ between DT pin and GND	1500	2000	2600	ns
t <sub>PW_MIN</sub>	Minimum input pulse width on INHx, INLx that changes the output on GHx, GLx		40	70	150	ns
BOOTSTRAP	DIODES(DRV8300UD, DRV8300UDI)				I	
\/	Poststron diado formanduraltana	I <sub>BOOT</sub> = 100 μA	0.45	0.7	0.85	V
V <sub>BOOTD</sub>	Bootstrap diode forward voltage	I <sub>BOOT</sub> = 100 mA	2	2.3	3.1	V
R <sub>BOOTD</sub>	Bootstrap dynamic resistance $(\Delta V_{BOOTD} / \Delta I_{BOOT})$	I <sub>BOOT</sub> = 100 mA and 80 mA	11	15	25	Ω
PROTECTION	I CIRCUITS	ł				
V	Gate Driver Supply undervoltage	Supply rising	8	8.3	8.6	V
V <sub>GVDDUV</sub>	lockout (GVDDUV)	Supply falling	7.8	8	8.25	V
V <sub>GVDDUV_HYS</sub>	Gate Driver Supply UV hysteresis	Rising to falling threshold	295	330	360	mV
t <sub>GVDDUV</sub>	Gate Driver Supply undervoltage deglitch time		5	10	13	μs



	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
V	Boot Strap undervoltage lockout (V <sub>BSTx</sub> - V <sub>SHx</sub> )	Supply rising	7.5	8	8.7	V
V <sub>BSTUV</sub>	Boot Strap undervoltage lockout (V <sub>BSTx</sub> - V <sub>SHx</sub> )	Supply falling	6.9	7.6	8.4	V
V <sub>BSTUV_HYS</sub>	Bootstrap UV hysteresis	Rising to falling threshold	250	400	850	mV
t <sub>BSTUV</sub>	Bootstrap undervoltage deglitch time		5.5	10	22	μs

### 7.6 Timing Diagrams

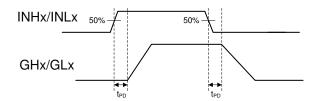
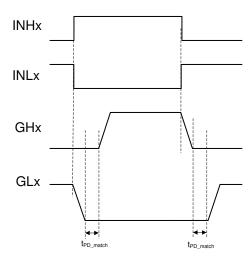
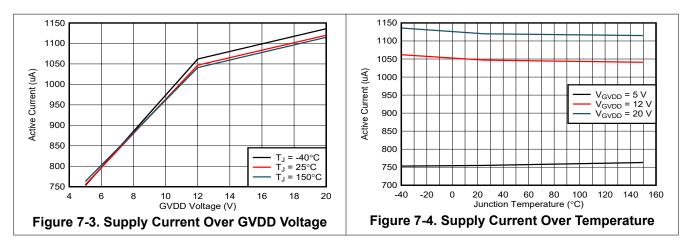


Figure 7-1. Propagation Delay(t<sub>PD</sub>)



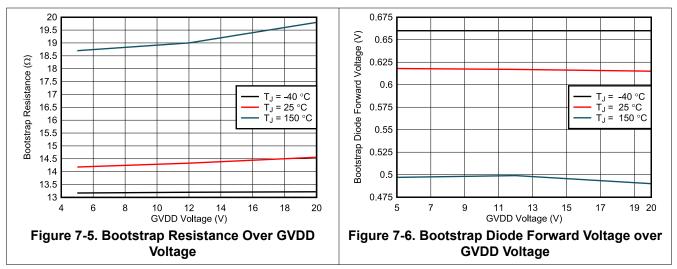


## 7.7 Typical Characteristics



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## 8 Detailed Description

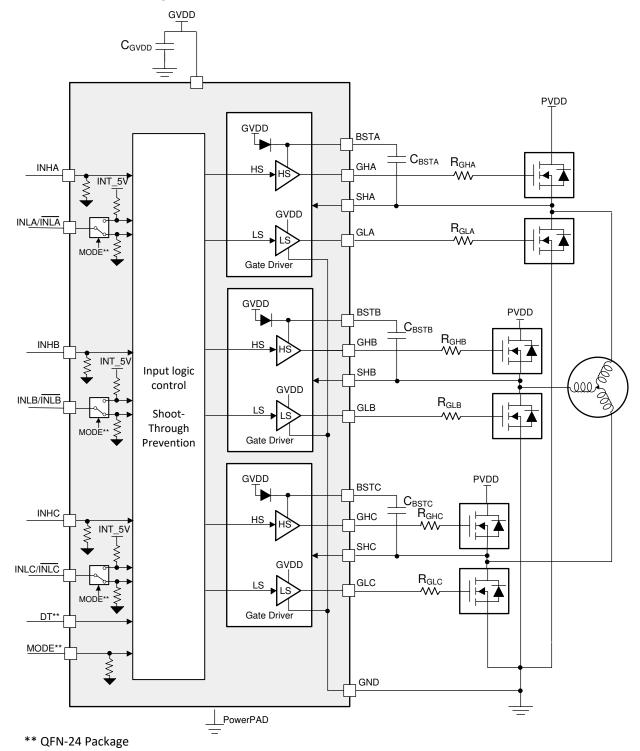
### 8.1 Overview

The DRV8300U family of devices is a gate driver for three-phase motor drive applications. These devices decrease system component count, saves PCB space and cost by integrating three independent half-bridge gate drivers and optional bootstrap diodes.

DRV8300U supports external N-channel high-side and low-side power MOSFETs and can drive 750-mA source, 1.5-A sink peak currents with total combined 30-mA average output current. The DRV8300U family of devices are available in 0.5-mm pitch QFN and 0.65-mm pitch TSSOP surface-mount packages. The QFN size is 4 × 4 mm (0.5-mm pin pitch) for the 24-pin package, and TSSOP body size is 6.5 × 4.4 mm (0.65-mm pin pitch) for the 20-pin package.



#### 8.2 Functional Block Diagram







#### 8.3 Feature Description

#### 8.3.1 Three BLDC Gate Drivers

The DRV8300U integrates three half-bridge gate drivers, each capable of driving high-side and low-side Nchannel power MOSFETs. Input on GVDD provides the gate bias voltage for the low-side MOSFETs. The high voltage is generated using bootstrap capacitor and GVDD supply. The half-bridge gate drivers can be used in combination to drive a three-phase motor or separately to drive other types of loads.

#### 8.3.1.1 Gate Drive Timings

#### 8.3.1.1.1 Propagation Delay

The propagation delay time  $(t_{pd})$  is measured as the time between an input logic edge to a detected output change. This time has two parts consisting of the input deglitcher delay and the delay through the analog gate drivers.

The input deglitcher prevents high-frequency noise on the input pins from affecting the output state of the gate drivers. The analog gate drivers have a small delay that contributes to the overall propagation delay of the device.

#### 8.3.1.1.2 Deadtime and Cross-Conduction Prevention

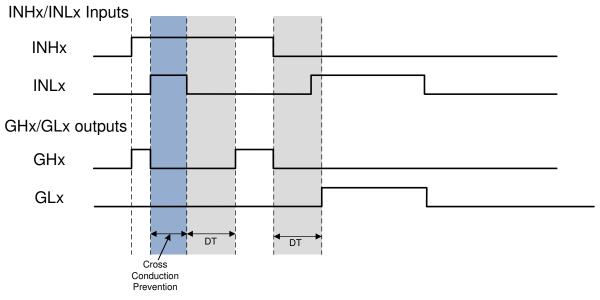
In the DRV8300U, high-side and low-side inputs operate independently, with an exception to prevent cross conduction when high and low side are turned ON at same time. The DRV8300U turns OFF high-side and low-side output to prevent shoot through when the both high-side and low-side inputs are at logic HIGH at same time.

The DRV8300U also provides option to insert additional deadtime to prevent the external high-side and low-side MOSFET from switching on at the same time. In the devices with DT pin (QFN package), deadtime can be linearly adjusted between 200 ns to 2000 ns by configuring resistor value between DT and GND. When the DT pin is left floating, fixed deadtime of 200 nS (typical value) is inserted. The value of resistor can be calculated using Equation 1.

$$R_{DT}(k\Omega) = \frac{Deadtime \ (nS)}{5}$$

(1)

In the devices without DT pin (TSSOP package), fixed deadtime of 200 ns (typical value) is inserted to prevent high and low side gate output turning ON at same time.

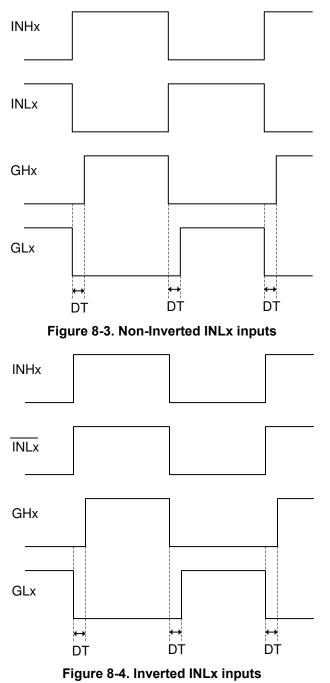






#### 8.3.1.2 Mode (Inverting and non inverting INLx)

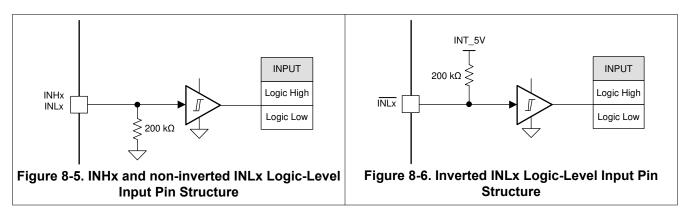
The DRV8300U has flexibility of accepting different kind of inputs on INLx. In the devices with MODE pin (QFN package), the DRV8300U provides option of configuring the GLx outputs to be inverted or non-inverted compared to polarity of signal on INLx pins. When the MODE pin is left floating, the INLx is configured to be in non-inverting mode and GLx output is in phase with respect to INLx (see Figure 8-3), whereas when the MODE pin is connected to GVDD, GLx output is out of phase with respect to INLx (see Figure 8-4). In devices without MODE pin (TSSOP package device), there are different device option available for inverting and non inverting inputs (see Section 5).





#### 8.3.2 Pin Diagrams

Figure 8-5 shows the input structure for the logic level pins INHx, INLx. INHx and non-inverted INLx has passive pull down, so when inputs are floating the output the gate driver will be pulled low. Figure 8-6 shows the input structure for the inverted INLx pins. The inverted INLx has passive pull up, so when inputs are floating the output of the low-side gate driver will be pulled low.



#### 8.3.3 Gate Driver Protective Circuits

The DRV8300U is protected against BSTx undervoltage and GVDD undervoltage events.

Table 8-1. I	Fault Action	and Res	ponse
--------------	--------------	---------	-------

FAULT	CONDITION	GATE DRIVER	RECOVERY
V <sub>BSTx</sub> undervoltage (BSTUV)	V <sub>BSTx</sub> < V <sub>BSTUV</sub>	GHx - Hi-Z	Automatic: V <sub>BSTx</sub> > V <sub>BSTUV</sub> and low to high PWM edge detected on INHx pin
GVDD undervoltage (GVDDUV)	V <sub>GVDD</sub> < V <sub>GVDDUV</sub>	Hi-Z	Automatic: V <sub>GVDD</sub> > V <sub>GVDDUV</sub>

### 8.3.3.1 V<sub>BSTx</sub> Undervoltage Lockout (BSTUV)

The DRV8300U has separate voltage comparator to detect undervoltage condition for each phases. If at any time the voltage on the BSTx pin falls lower than the  $V_{BSTUV}$  threshold, high side external MOSFETs of that particular phase is disabled by disabling (Hi-Z) GHx pin. Normal operation starts again when the BSTUV condition clears and low to high PWM edge is detected on INHx input of the same phase that BSTUV condition was detected. BSTUV protection ensures that high-side MOSFETs are not driven when the BSTx pins has lower value.

### 8.3.3.2 GVDD Undervoltage Lockout (GVDDUV)

If at any time the voltage on the GVDD pin falls lower than the  $V_{GVDDUV}$  threshold voltage, all of the external MOSFETs are disabled. Normal operation starts again when the GVDDUV condition clears. GVDDUV protection ensures that external MOSFETs are not driven when the GVDD input is at lower value.

#### 8.4 Device Functional Modes

The DRV8300U is in operating (active) mode, whenever the GVDD and BST pins are higher than the UV threshold (GVDD >  $V_{GVDDUV}$ and  $V_{BSTX}$  >  $V_{BSTUV}$ ). In active mode, the gate driver output GHx and GLX will follow respective inputs INHx and INLx.



## **9** Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

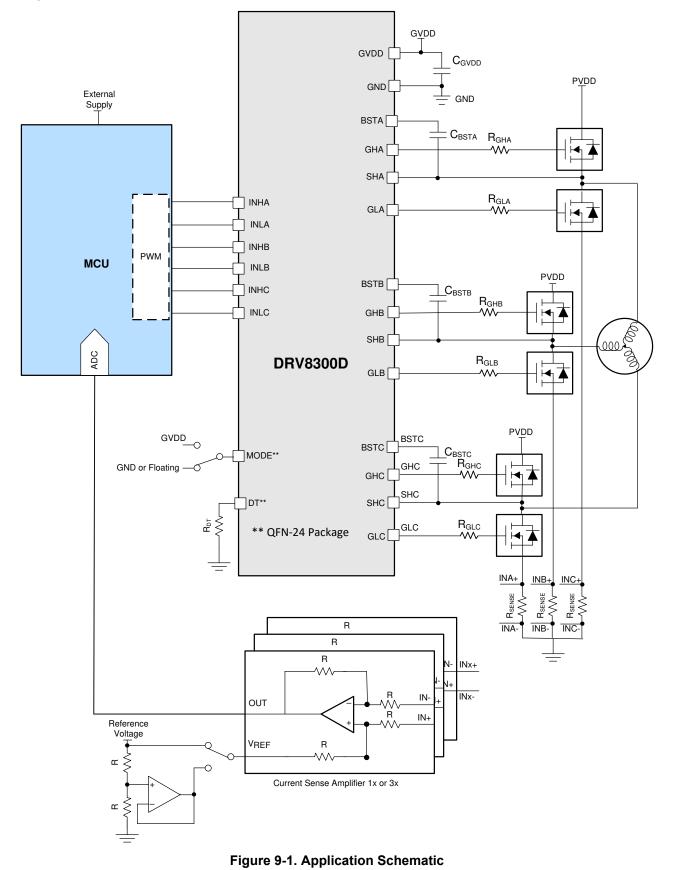
#### 9.1 Application Information

The DRV8300U family of devices is primarily used in applications for three-phase brushless DC motor control. The design procedures in the *Section 9.2* section highlight how to use and configure the DRV8300U.



## 9.2 Typical Application

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#### 9.2.1 Design Requirements

Table 9-1 lists the example design input parameters for system design.

EXAMPLE DESIGN PARAMETER	REFERENCE	EXAMPLE VALUE							
MOSFET	-	CSD19532Q5B							
Gate Supply Voltage	V <sub>GVDD</sub>	12 V							
Gate Charge	Q <sub>G</sub>	48 nC							

## Table 9-1, Design Parameters

#### 9.2.2 Bootstrap Capacitor and GVDD Capacitor Selection

The bootstrap capacitor must be sized to maintain the bootstrap voltage above the undervoltage lockout for normal operation. Equation 2 calculates the maximum allowable voltage drop across the bootstrap capacitor:

$$\Delta V_{BSTX} = V_{GVDD} - V_{BOOTD} - V_{BSTUV}$$

=12 V - 0.85 V - 4.5 V = 6.65 V

where

- V<sub>GVDD</sub> is the supply voltage of the gate drive
- V<sub>BOOTD</sub> is the forward voltage drop of the bootstrap diode
- V<sub>BSTUV</sub> is the threshold of the bootstrap undervoltage lockout

In this example the allowed voltage drop across bootstrap capacitor is 6.65 V. It is generally recommended that ripple voltage on both the bootstrap capacitor and GVDD capacitor should be minimized as much as possible. Many of commercial, industrial, and automotive applications use ripple value between 0.5 V to 1 V.

The total charge needed per switching cycle can be estimated with Equation 3:

$$Q_{TOT} = Q_G + \frac{IL_{BS\_TRANS}}{f_{SW}}$$
(3)

=48 nC + 220 µA/20 kHz = 50 nC + 11 nC = 59 nC

where

- Q<sub>G</sub> is the total MOSFET gate charge
- ILBS TRAN is the bootstrap pin leakage current
- f<sub>SW</sub> is the is the PWM frequency

The minimum bootstrap capacitor an then be estimated as below assuming  $1V \Delta V_{BSTx}$ :

$$C_{BST\_MIN} = \frac{Q_{TOT}}{\Delta V_{BSTX}}$$

= 59 nC / 1 V = 59 nF

The calculated value of minimum bootstrap capacitor is 59 nF. It should be noted that, this value of capacitance is needed at full bias voltage. In practice, the value of the bootstrap capacitor must be greater than calculated value to allow for situations where the power stage may skip pulse due to various transient conditions. It is recommended to use a 100 nF bootstrap capacitor in this example. It is also recommenced to include enough margin and place the bootstrap capacitor as close to the BSTx and SHx pins as possible.

Product Folder Links: DRV8300U

$$C_{GVDD} \geq 10 \times C_{BSTX}$$

18 Submit Document Feedback (2)

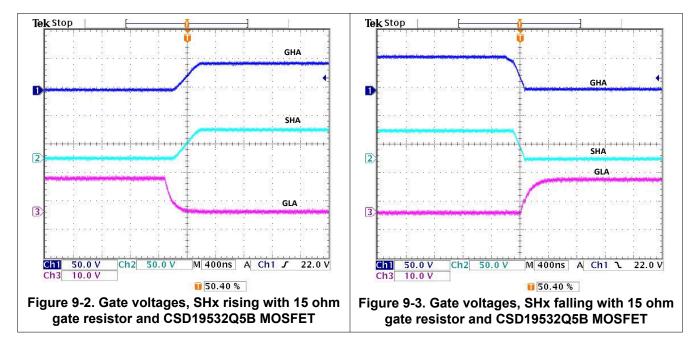
(4)

(5)



For this example application choose 1  $\mu$ F C<sub>GVDD</sub> capacitor. Choose a capacitor with a voltage rating at least twice the maximum voltage that it will be exposed to because most ceramic capacitors lose significant capacitance when biased. This value also improves the long term reliability of the system.

#### 9.2.3 Application Curves





## **10 Power Supply Recommendations**

The DRV8300U is designed to operate from an input voltage supply (GVDD) range from 4.8 V to 20 V. A local bypass capacitor should be placed between the GVDD and GND pins. This capacitor should be located as close to the device as possible. A low ESR, ceramic surface mount capacitor is recommended. It is recommended to use two capacitors across GVDD and GND: a low capacitance ceramic surface-mount capacitor for high frequency filtering placed very close to GVDD and GND pin, and another high capacitance value surfacemount capacitor for device bias requirements. In a similar manner, the current pulses delivered by the GHx pins are sourced from the BSTx pins. Therefore, capacitor across the BSTx to SHx is recommended, it should be high enough capacitance value capacitor to deliver GHx pulses

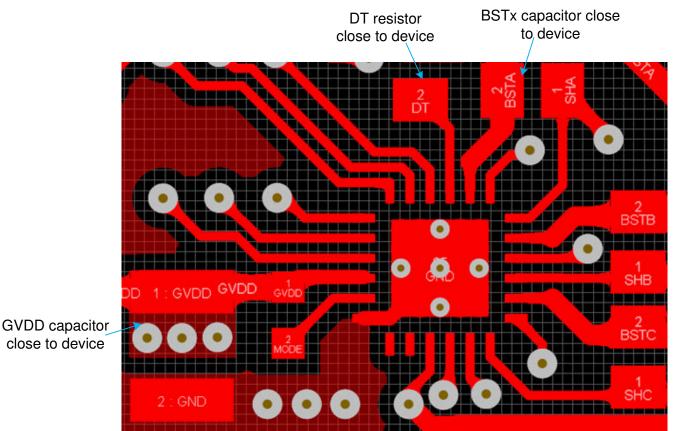


## 11 Layout

## 11.1 Layout Guidelines

- Low ESR/ESL capacitors must be connected close to the device between GVDD and GND and between BSTx and SHx pins to support high peak currents drawn from GVDD and BSTx pins during the turn-on of the external MOSFETs.
- To prevent large voltage transients at the drain of the top MOSFET, a low ESR electrolytic capacitor and a good quality ceramic capacitor must be connected between the high side MOSFET drain and ground.
- In order to avoid large negative transients on the switch node (SHx) pin, the parasitic inductances between the source of the high-side MOSFET and the source of the low-side MOSFET must be minimized.
- In order to avoid unexpected transients, the parasitic inductance of the GHx, SHx, and GLx connections must be minimized. Minimize the trace length and number of vias wherever possible. Minimum 10 mil and typical 15 mil trace width is recommended.
- Resistance between DT and GND must be place as close as possible to device
- Place the gate driver as close to the MOSFETs as possible. Confine the high peak currents that charge and discharge the MOSFET gates to a minimal physical area by reducing trace length. This confinement decreases the loop inductance and minimize noise issues on the gate terminals of the MOSFETs.
- In QFN package device variants, NC pins can be connected to GND to increase ground conenction between thermal pad and external ground plane.
- Refer to sections General Routing Techniques and MOSFET Placement and Power Stage Routing in Application Report

### 11.2 Layout Example





## 12 Device and Documentation Support

### **12.1 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### **12.2 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 12.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 12.5 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DRV8300UDPWR	ACTIVE	TSSOP	PW	20	3000	RoHS & Green	(6) NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8300UD	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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## TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal	

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DRV8300UDPWR	TSSOP	PW	20	3000	330.0	16.4	6.95	7.1	1.6	8.0	16.0	Q1



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# PACKAGE MATERIALS INFORMATION

15-Sep-2022



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DRV8300UDPWR	TSSOP	PW	20	3000	356.0	356.0	35.0

# **PW0020A**



# **PACKAGE OUTLINE**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice. 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.



# PW0020A

# **EXAMPLE BOARD LAYOUT**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# PW0020A

# **EXAMPLE STENCIL DESIGN**

## TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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